

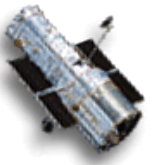
COS + STIS Update

Cristina Oliveira





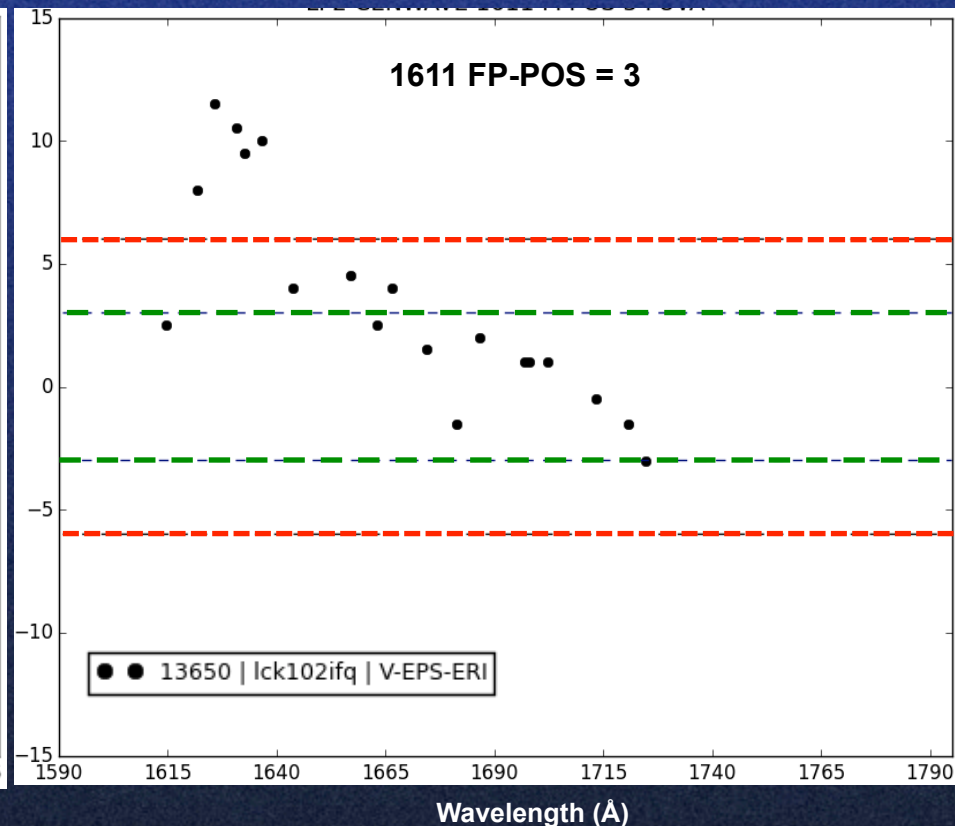
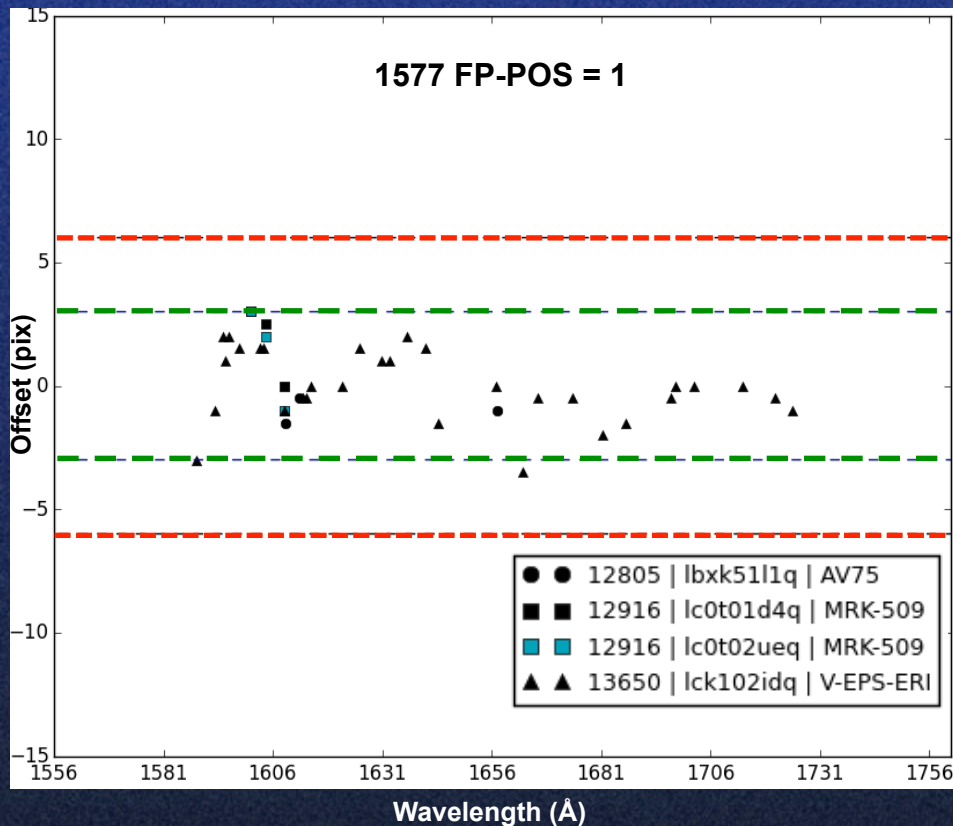
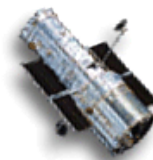
COS/FUV Wavelength Calibration



- Currently the highest priority work of the COS/STIS team
 - Working group in place since late June 2015: C. Oliveira (chair), T. Ake, J. Ely, S. Penton, R. Plesha, C. Proffitt, J. Roman-Duval, D. Sahnou, and P. Sonnentrucker
- Pursuing 3 major tasks under this working group
 1. Improve wavelength calibration using STIS wavelength calibration as reference
 - Expect to have updated coefficients by early 2016, for the most used settings
 2. Improve x-walk correction
 3. Improve geometric distortion correction
- ➔ *Goal is to have dispersion solution accurate to within +/- 3 pix (~10 km/s) for M gratings (1 σ) - initial requirement was +/- 6 pix or ~20 km/s*
- Executive summary of what we have achieved so far
 1. Have derived preliminary linear dispersions solutions for many settings – for a large number of settings (cenwave/seg/LP/FP) the residuals are within +/- 3 pix
 2. x-walk can be as much as ~6 pix in certain areas of the detector
 3. Preliminary analysis of TV03 geometric correction data indicates that ~87% of the lines used in the analysis have dispersion errors < 3 pix (data probes effects on the scale of 30 to 200 pix) – geometric correction residuals not a major contributor



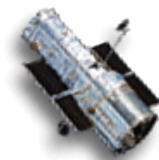
Cross-Correlation Offsets G160M LP2 - FUV



- Eps Eri exposures obtained in same 1 orbit visit, consecutively
- TA issues affect both exposures equally, data clearly indicate issue with 1611 dispersion solution.

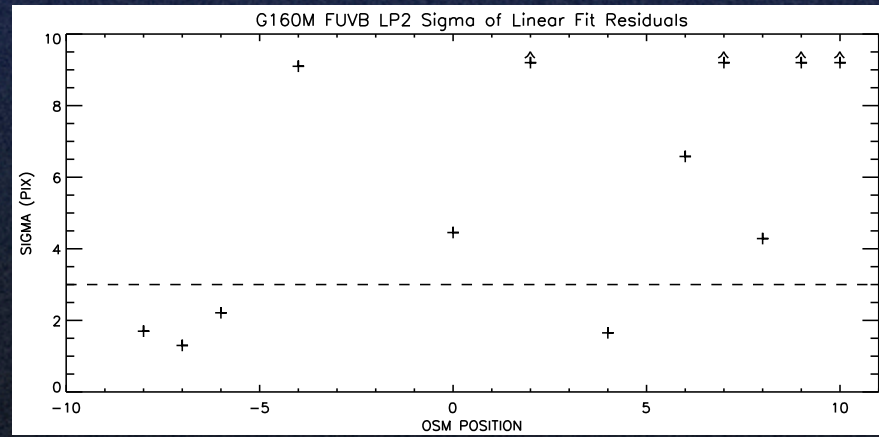
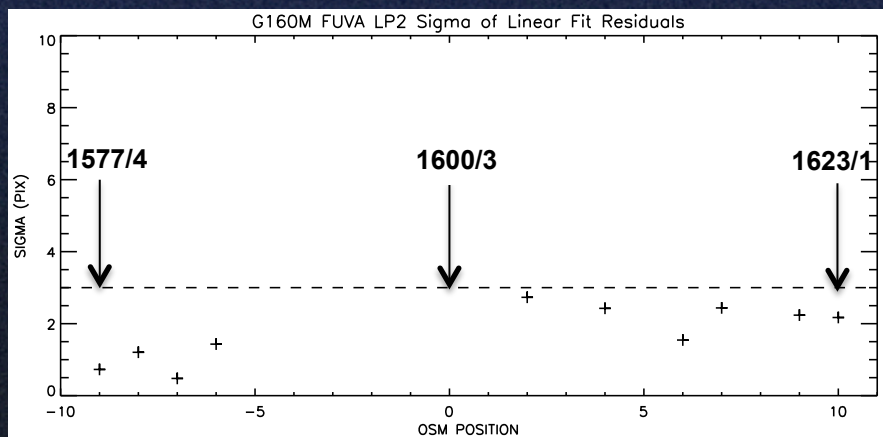
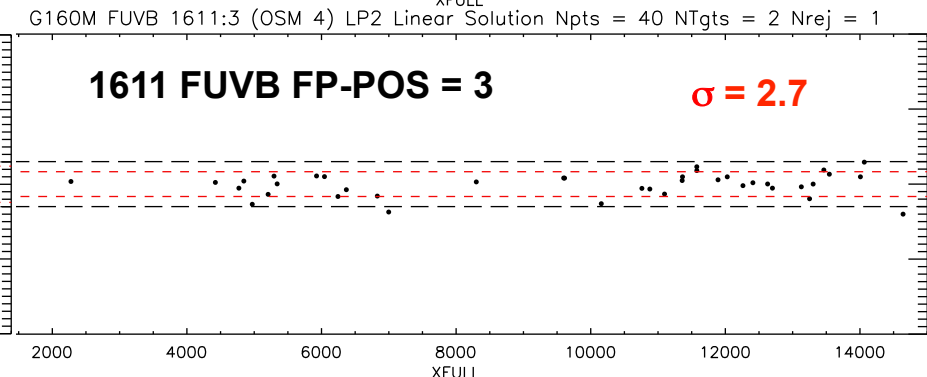
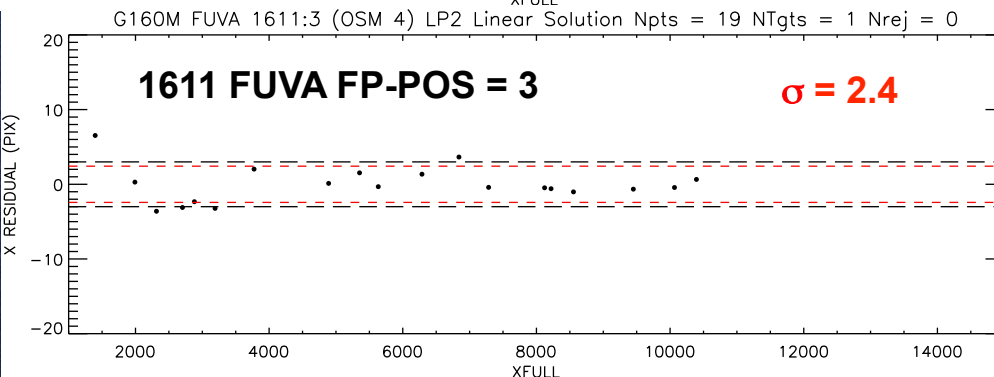
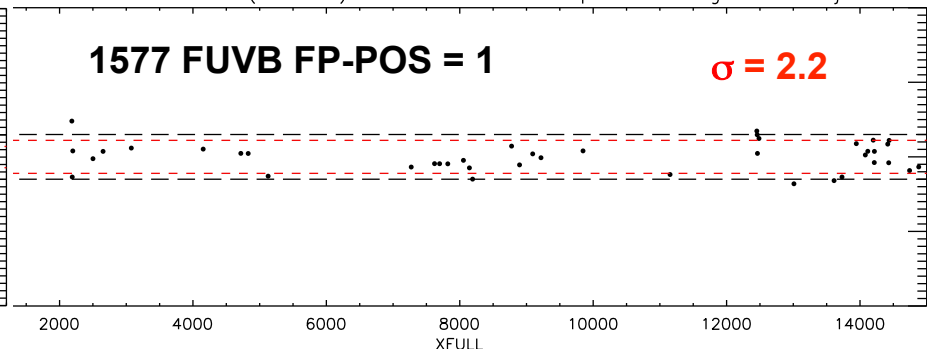
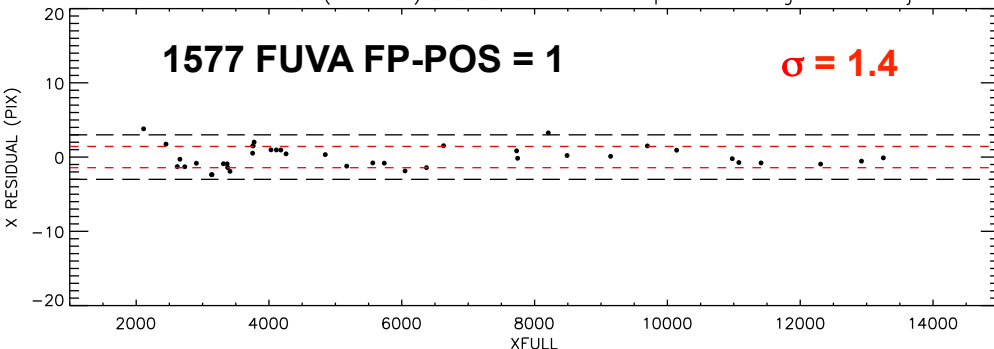


Preliminary Dispersion Solutions G160M/LP2



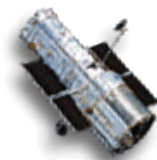
G160M FUVA 1577:1 (OSM -6) LP2 Linear Solution Npts = 40 NTgts = 3 Nrej = 0

G160M FUVB 1577:1 (OSM -6) LP2 Linear Solution Npts = 44 NTgts = 3 Nrej = 0





Preliminary Dispersion Solutions G130M/FUVA/LP1



G130M FUVA 1291:4 (OSM -9) LP1 Linear Solution Npts = 72 NTgts = 6 Nrej = 0

1291 FP-POS = 4

$\sigma = 1.9$

black = +/- 3 pix goal
red = 1 sigma of residuals

G130M FUVA 1291:3 (OSM -8) LP1 Linear Solution Npts = 101 NTgts = 12 Nrej = 2

1291 FP-POS = 3

$\sigma = 2.0$

(offsets shown in slide 6)

G130M FUVA 1309:4 (OSM -1) LP1 Linear Solution Npts = 57 NTgts = 4 Nrej = 0

1309 FP-POS = 4

$\sigma = 1.7$

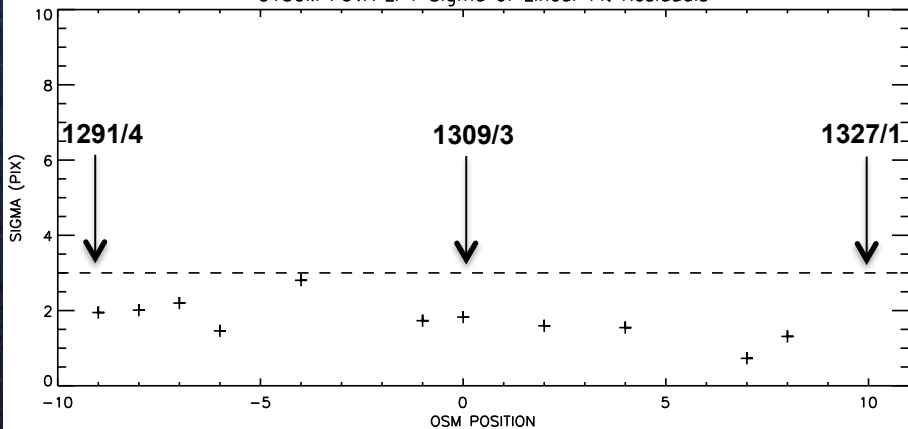
G130M FUVA 1309:3 (OSM 0) LP1 Linear Solution Npts = 98 NTgts = 10 Nrej = 1

1309 FP-POS = 3

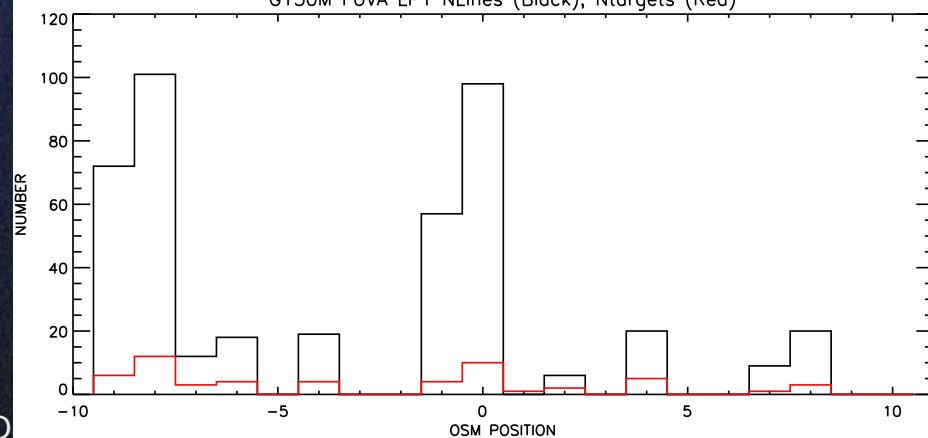
$\sigma = 1.8$

(offsets shown in slide 6)

G130M FUVA LP1 Sigma of Linear Fit Residuals

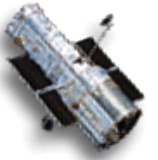


G130M FUVA LP1 NLines (Black), Ntargets (Red)





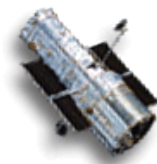
Detector Walk



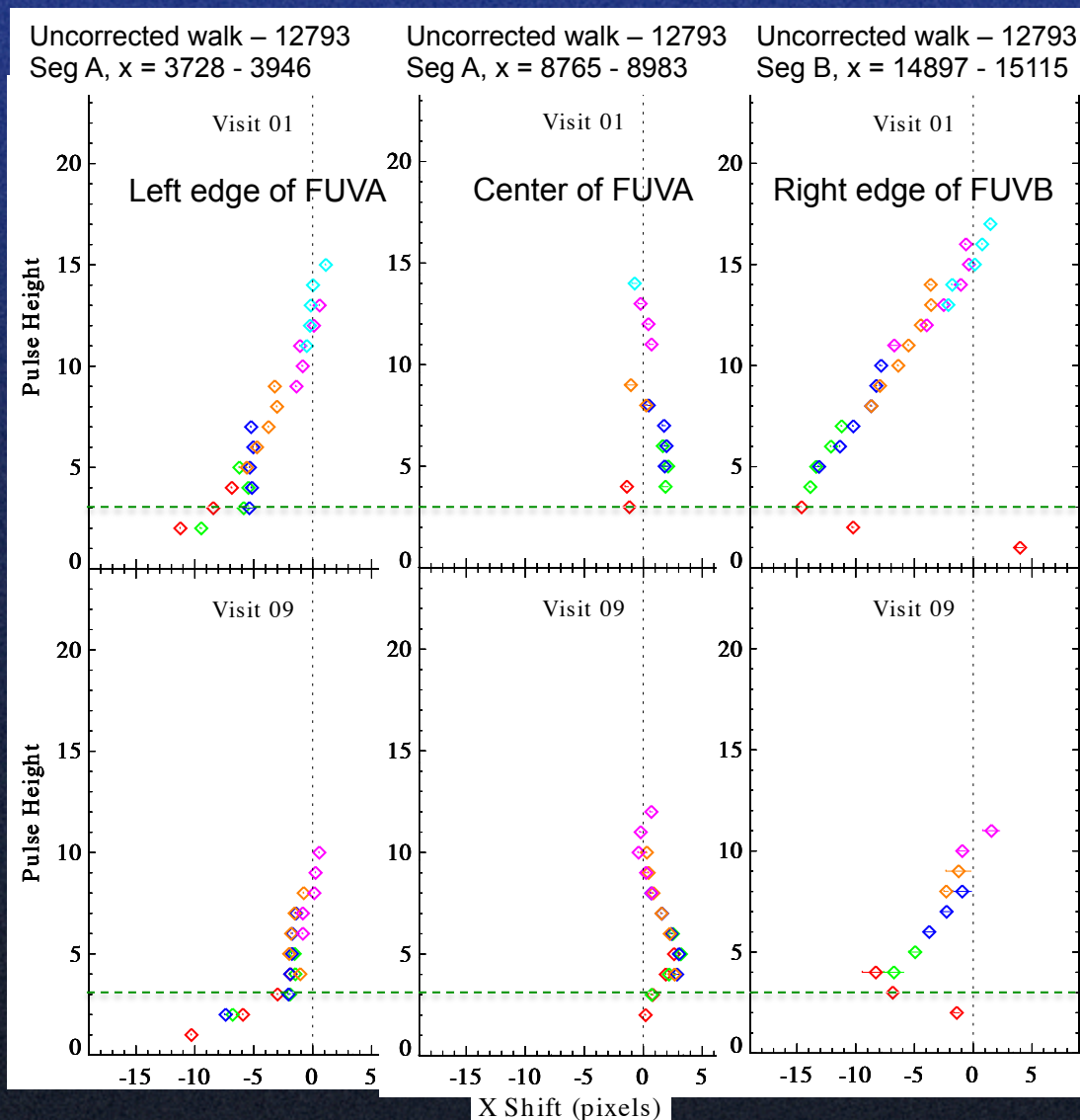
- Detector walk is the dependence of the calculated photon position on the pulse height (see e.g. Sahnou et al., 2011, SPIE proceedings, Vol 8859)
- Affects both the dispersion (x-walk) and cross-dispersion (y-walk) directions
- Figures in next slide are “interesting” examples of x-walk in the COS/FUV detector
 - x-walk is worse in some localized areas
- COS pipeline
 - Y-walk correction is currently applied
 - No x-walk correction is implemented



Walk Correction

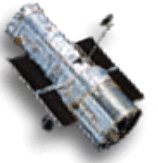


- Analyzing lamp data taken at different HV to evaluate x- and y-walk
 - Want to determine how the registration of events on the detector varies depending on the PHA
 - Affects both the dispersion (x) and cross-dispersion directions (y)
 - COS pipeline contains currently a y-walk correction only, that will be revisited in this work. Higher priority is to tackle the x-walk
 - x-walk varies in detector and in some areas can be up to ~6 pix, over the PHA range used in normal operations (PHA > 3, marked by green dashed line)
 - Edges of the detector are worse

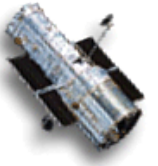




Updating Dispersion Solutions Ongoing Work



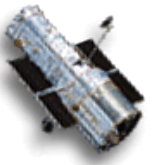
- Need to access if # of lines used to determine dispersion coefficients and their distribution on the detector is adequate
- Identify datasets where TA uncertainty is minimal and use those datasets to derive zero-point of wavelength solution
- Use AGN dataset compiled by B. Wakker and C. Danforth in addition to other datasets to test new dispersion solutions
 - Current wavelength dispersion reference file can support up to $n=3$ polynomial
 - No changes to pipeline required, only updated ref file, no other dependencies
- Investigate if difference between LP1 and LP2 dispersion coefficients is significant – both with models and from data
- Explore ray-trace models and see if can explain discrepancy between models and new coefficients by adjusting the focus in the models
 - If so, might be able to use ray-trace models coefficients for settings for which we have no overlapping COS + STIS data
- Release updated dispersion coefficients for most used settings in early 2016 and full set by ~ Summer 2016
- To improve dispersion solutions beyond ± 3 pix (and to that level in some localized regions) will need to improve x-walk and geometric distortion corrections



BACK-UP SLIDES



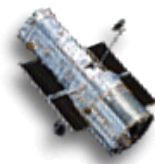
COS/FUV Wavelength Calibration



- Currently the highest priority work of the COS/STIS team
 - Working group in place since late June 2015: C. Oliveira (chair), T. Ake, J. Ely, S. Penton, R. Plesha, C. Proffitt, J. Roman-Duval, D. Sahnou, and P. Sonnentrucker
- Pursuing 3 major tasks under this working group
 1. Improve wavelength calibration using STIS wavelength calibration as reference
 - Expect to have updated coefficients by early 2016, for the most used settings
 2. Improve x-walk correction
 3. Improve geometric distortion correction
- ➔ *Goal is to have dispersion solution accurate to within +/- 3 pix (~10 km/s) for M gratings (1 σ) - initial requirement was +/- 6 pix or ~20 km/s*
- Executive summary of what we have achieved so far
 1. Have derived preliminary linear dispersions solutions for many settings – for a large number of settings (cenwave/seg/LP/FP) the residuals are within +/- 3 pix
 2. x-walk can be as much as ~6 pix in certain areas of the detector
 3. Preliminary analysis of TV03 geometric correction data indicates that ~87% of the lines used in the analysis have dispersion errors < 3 pix (data probes effects on the scale of 30 to 200 pix) – geometric correction residuals not a major contributor



COS/FUV Detector



COS/FUV detectors are analog – signal is digitized at the end. No physical pixels.

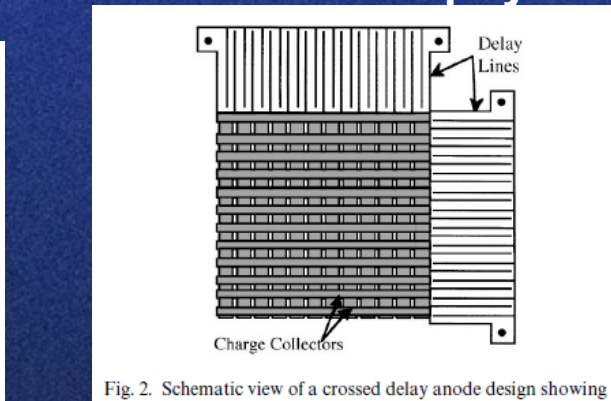
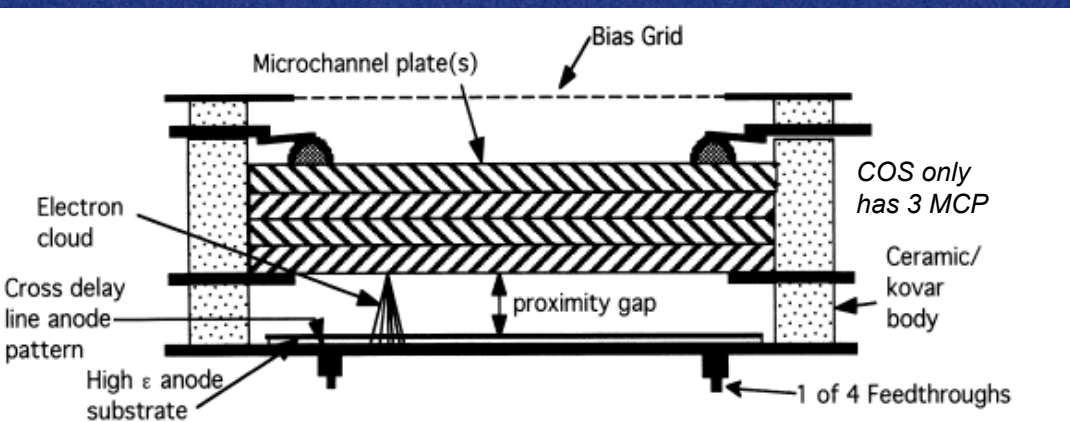
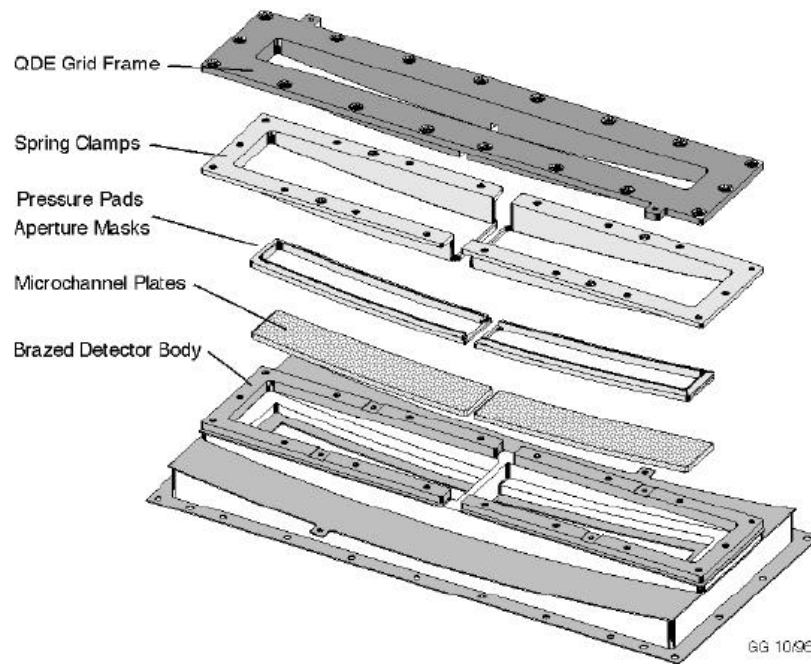
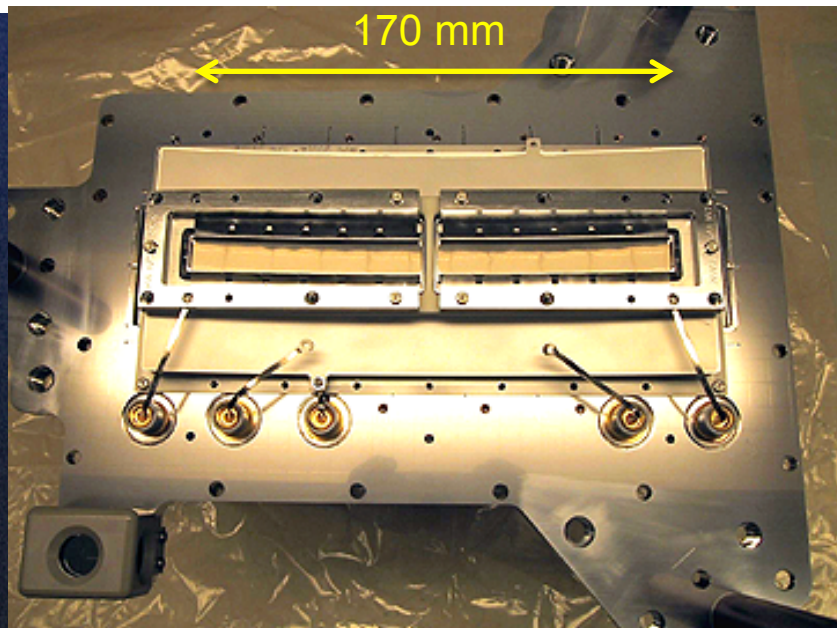


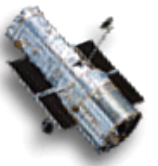
Fig. 2. Schematic view of a crossed delay anode design showing the X and Y charge collection fingers and external delay lines.



GG 1096



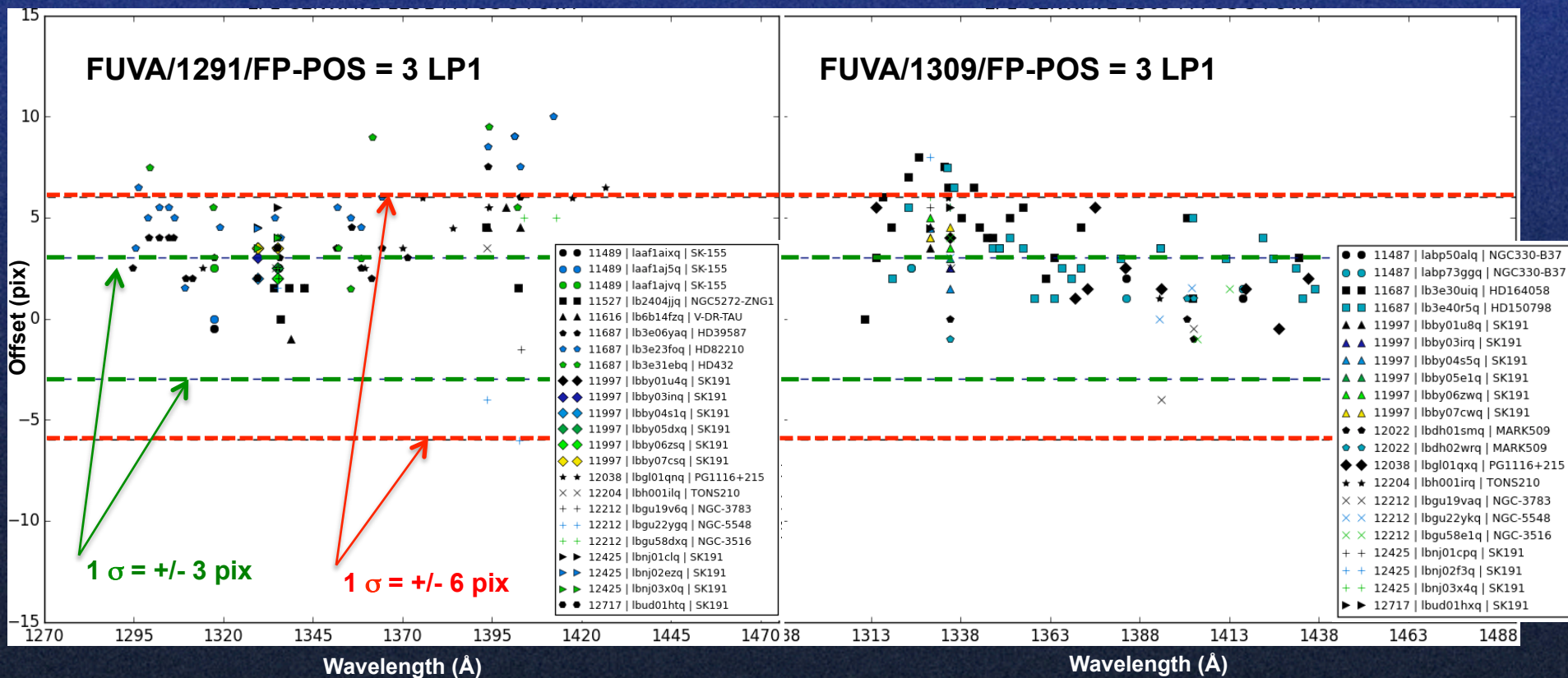
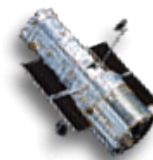
COS/FUV Wavelength Calibration: Using STIS as Reference



- Effort is focused on improving the G130M and G160M dispersion solutions
 - These are the gratings used by most of the people that need an improved λ solution
 - Current dispersion solutions used by CalCOS are linear, we are investigating linear and quadratic fits
- Have 25 targets that have COS (G130M, G160M) and STIS (E140H, E140M, E230H, E230M) data
 - STIS wavelength accuracy is at least 0.5 km/s (H gratings) and 1.5 km/s (M gratings)
 - For each target, wavelength windows with emission/absorption features were carefully selected, with the goal of maximizing wavelength coverage, while avoiding variable stellar wind lines and regions of airglow in the COS/FUV data (~640 unique windows)
 - For which window, the COS and STIS data are cross-correlated so that a shift can be determined (~7300 COS windows used)
 - Lines at the edge of detector are discarded, and DQ values are taken into account
 - Lifetime positions (LP), cenwaves, and FP-POS are being kept separate at this point
 - For some targets the TA strategy might not be optimal for this purpose – zero point of the wavelength scale will be affected, but valuable information can still be extracted from the data
 - Targets with best-centering TA will be used to bootstrap settings where zero-point might not be accurate, can be expanded to targets without STIS data

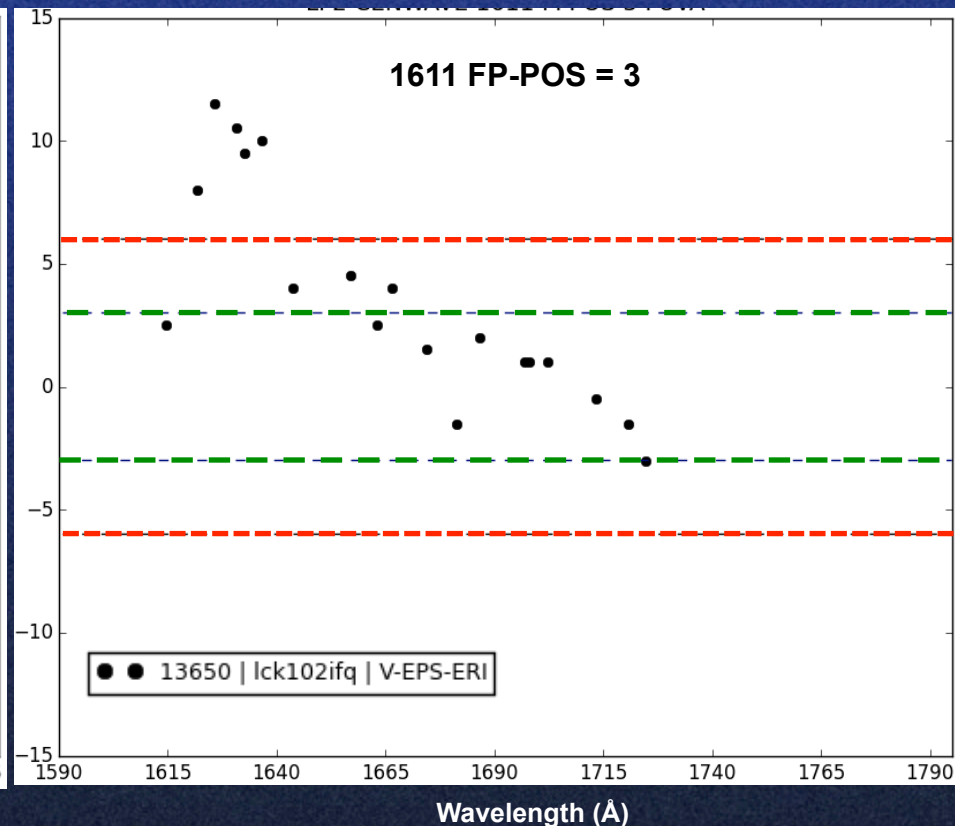
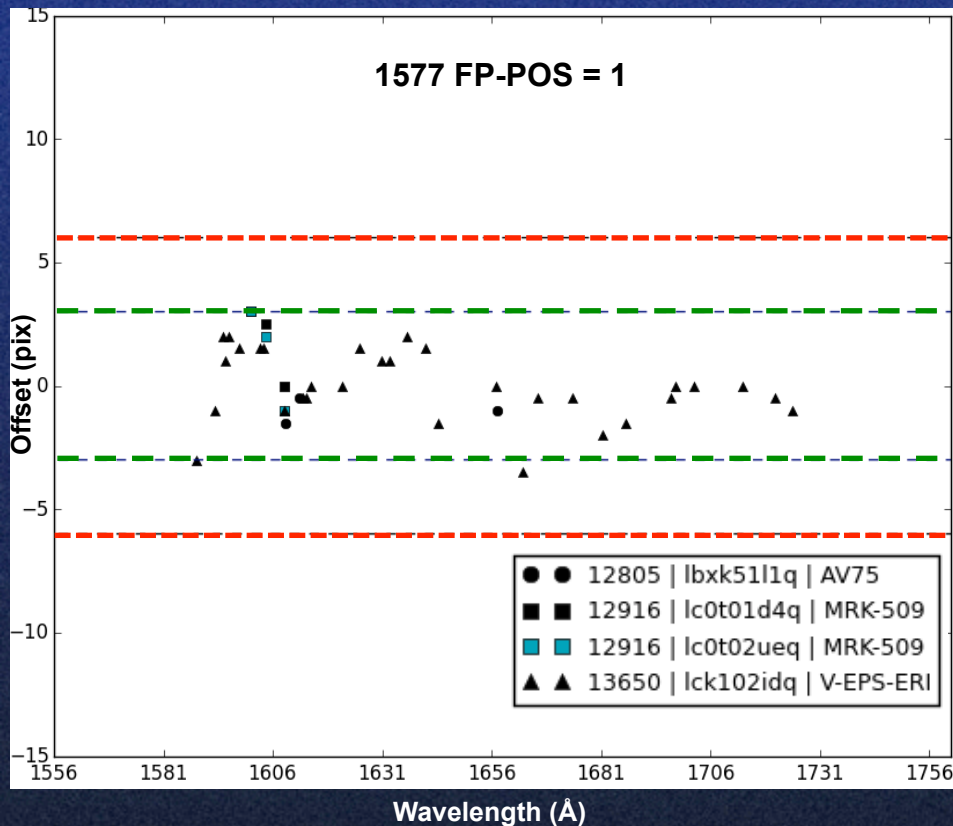
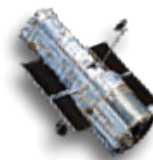


Cross-Correlation Offsets





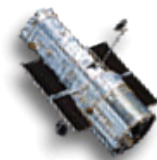
Cross-Correlation Offsets G160M LP2 - FUVA



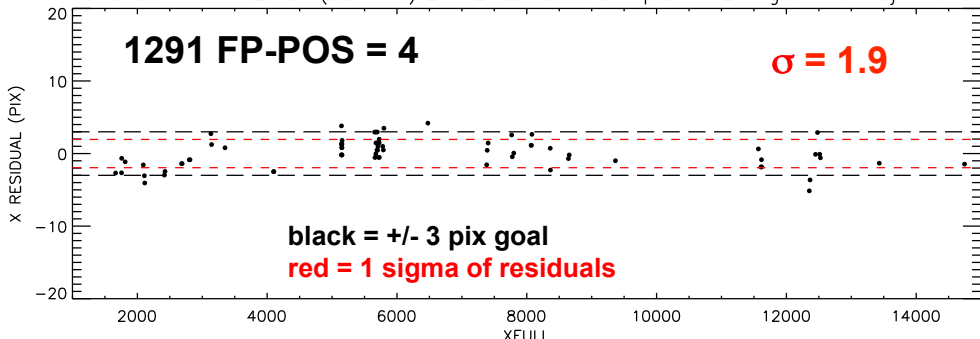
- Eps Eri exposures obtained in same 1 orbit visit, consecutively
- TA issues affect both exposures equally, data clearly indicate issue with 1611 dispersion solution.



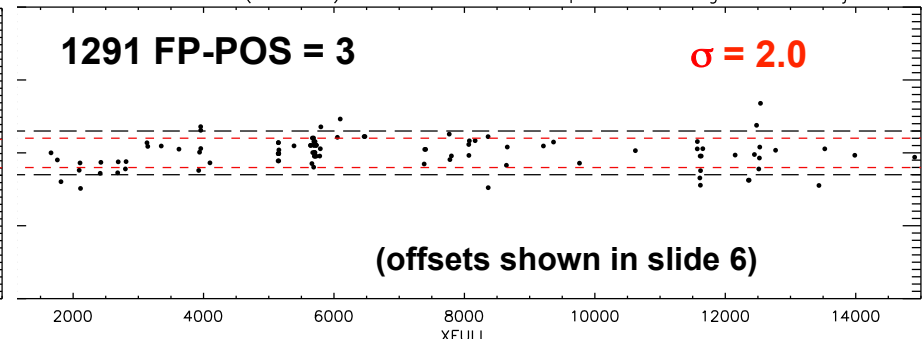
Preliminary Dispersion Solutions G130M/FUVA/LP1



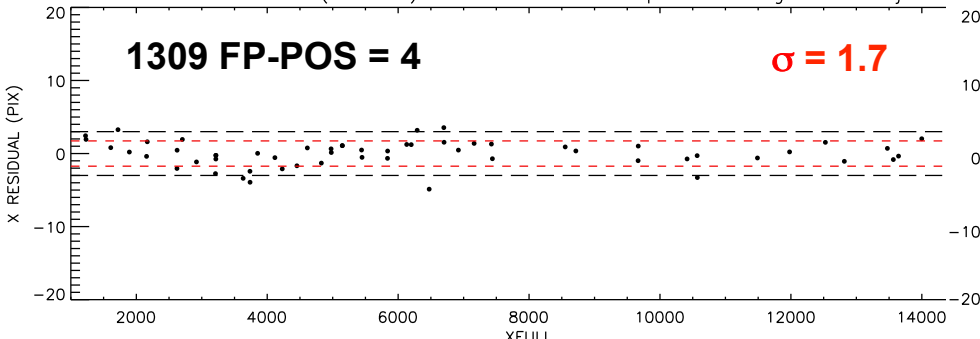
G130M FUVA 1291:4 (OSM -9) LP1 Linear Solution Npts = 72 NTgts = 6 Nrej = 0



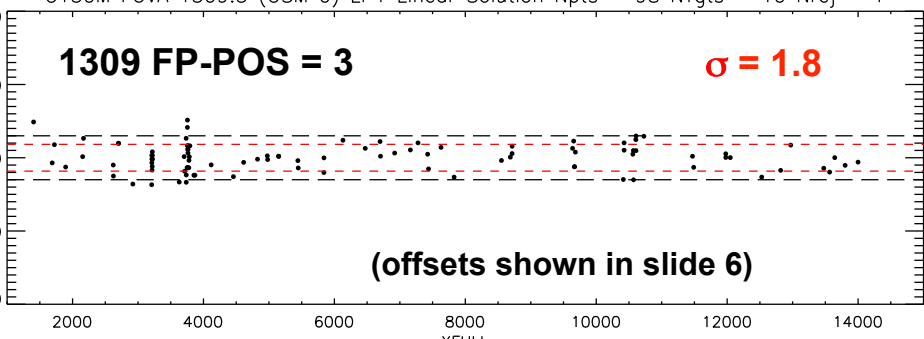
G130M FUVA 1291:3 (OSM -8) LP1 Linear Solution Npts = 101 NTgts = 12 Nrej = 2



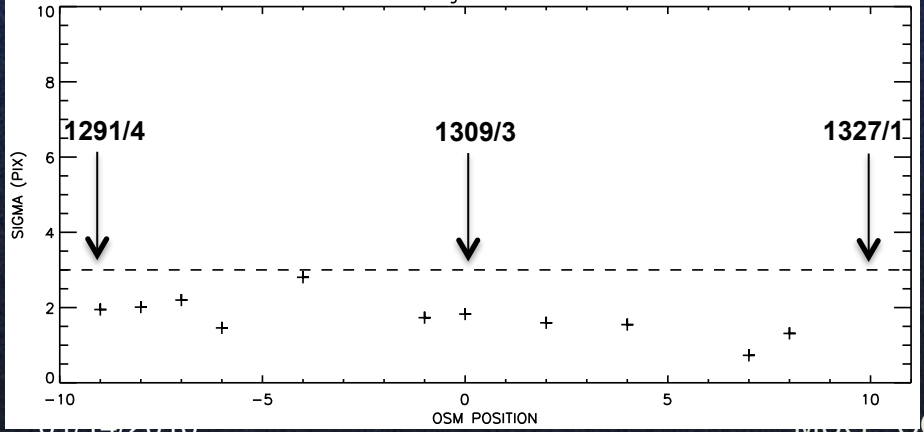
G130M FUVA 1309:4 (OSM -1) LP1 Linear Solution Npts = 57 NTgts = 4 Nrej = 0



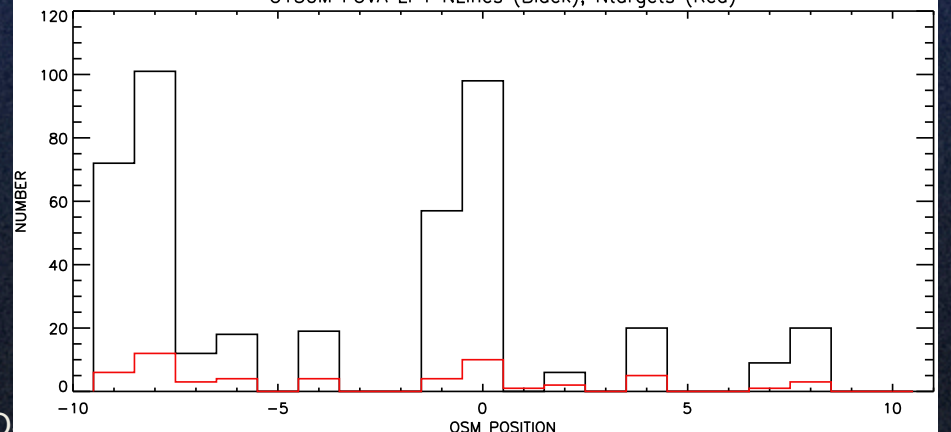
G130M FUVA 1309:3 (OSM 0) LP1 Linear Solution Npts = 98 NTgts = 10 Nrej = 1



G130M FUVA LP1 Sigma of Linear Fit Residuals

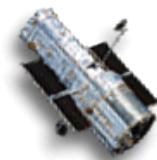


G130M FUVA LP1 NLines (Black), Ntargets (Red)



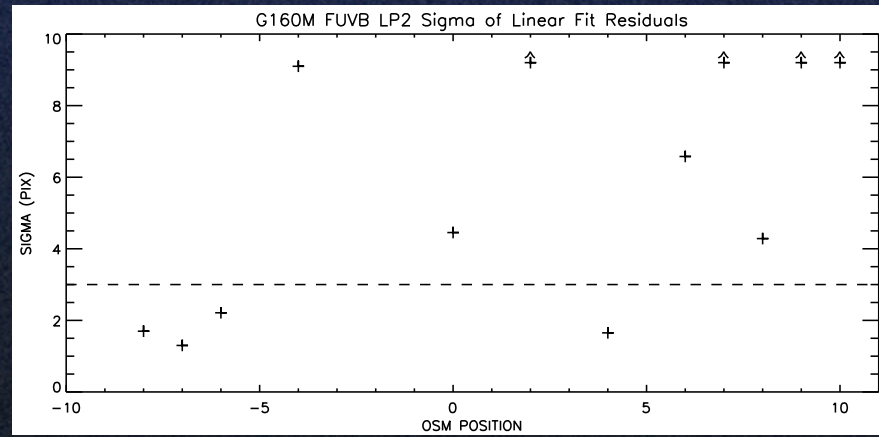
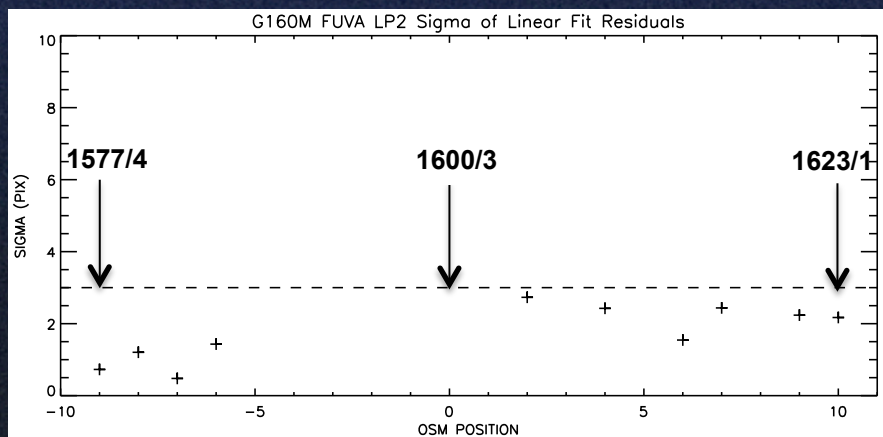
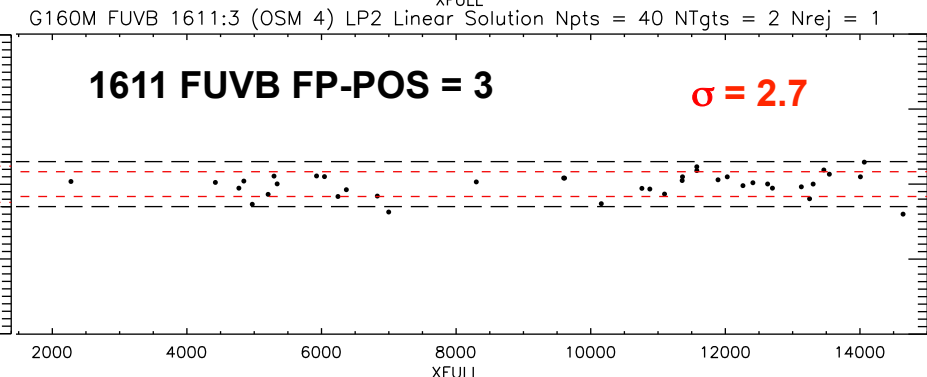
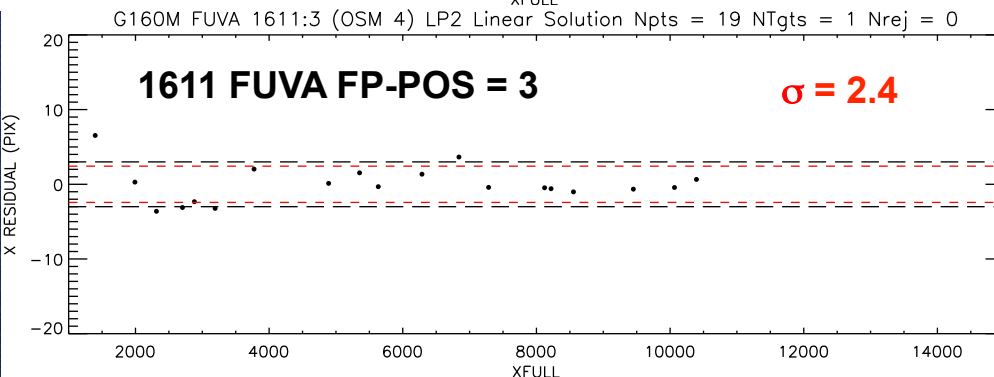
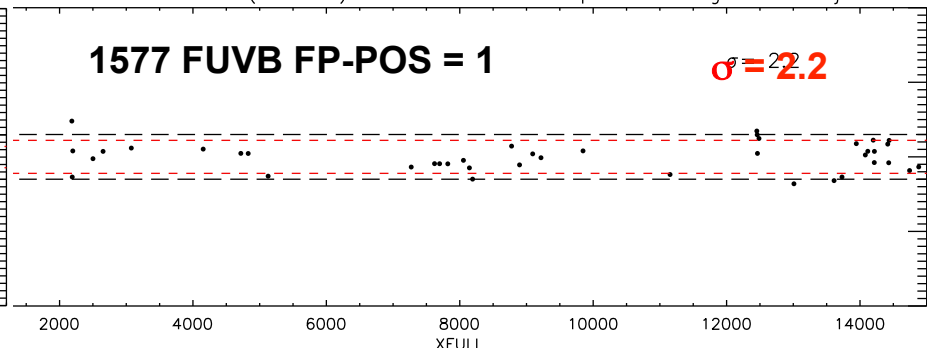
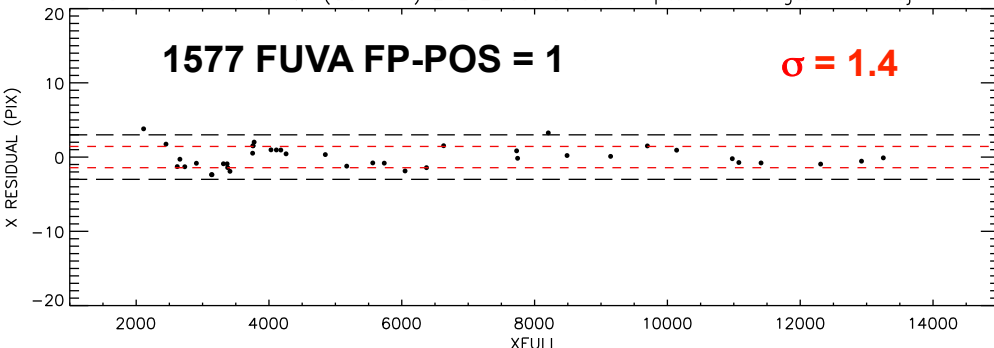


Preliminary Dispersion Solutions G160M/LP2



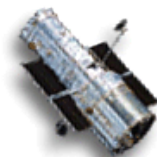
G160M FUVA 1577:1 (OSM -6) LP2 Linear Solution Npts = 40 NTgts = 3 Nrej = 0

G160M FUVB 1577:1 (OSM -6) LP2 Linear Solution Npts = 44 NTgts = 3 Nrej = 0

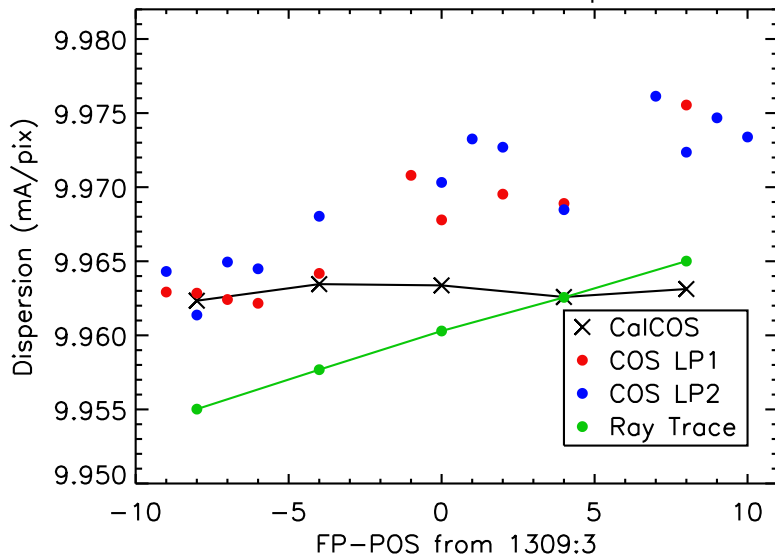




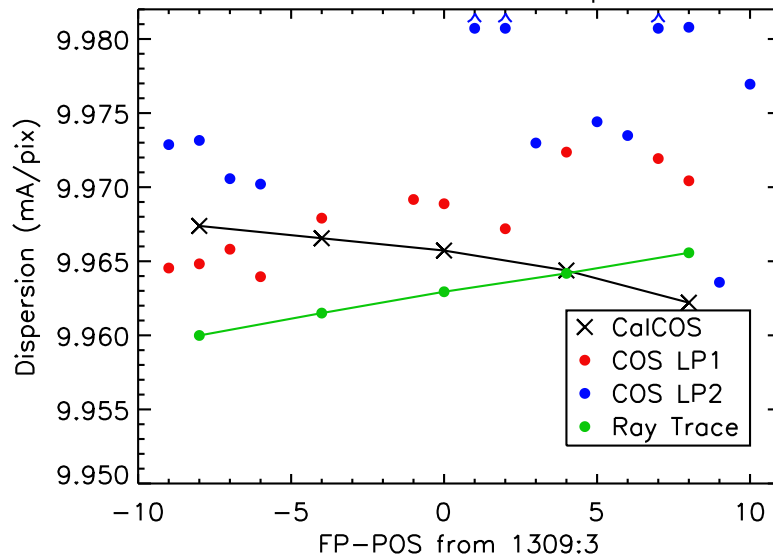
What about Ray Trace Models?



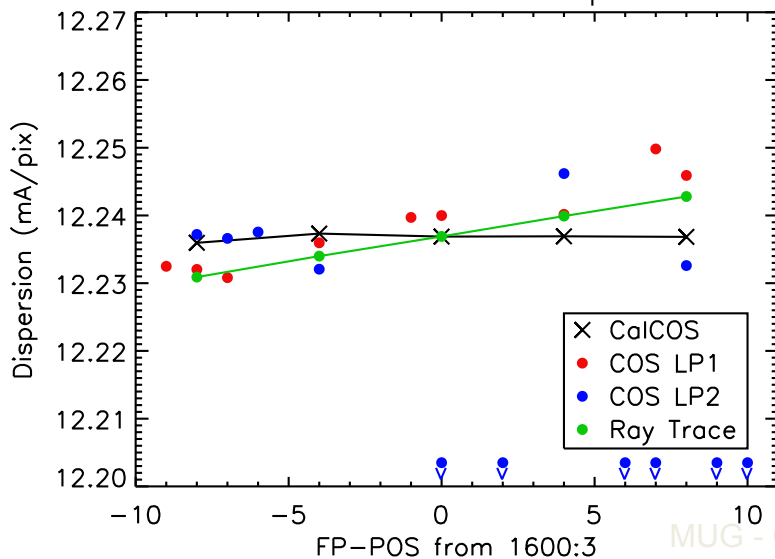
G130M FUVB Linear Dispersion



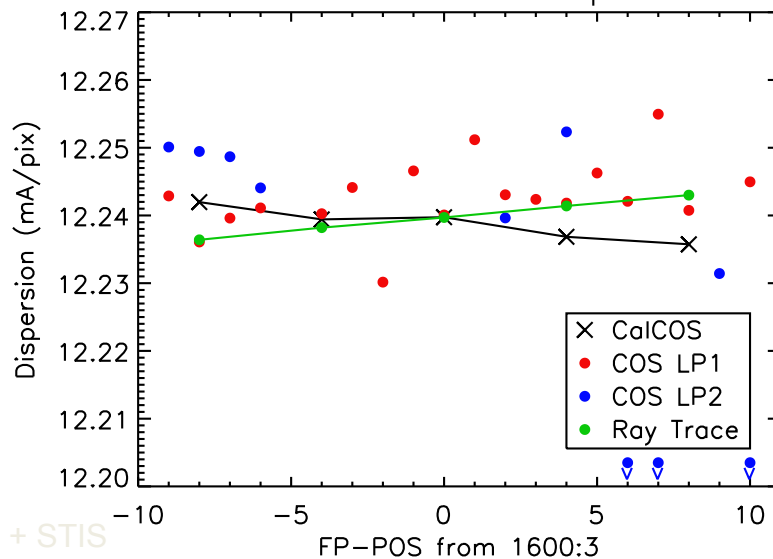
G130M FUGA Linear Dispersion



G160M FUVB Linear Dispersion

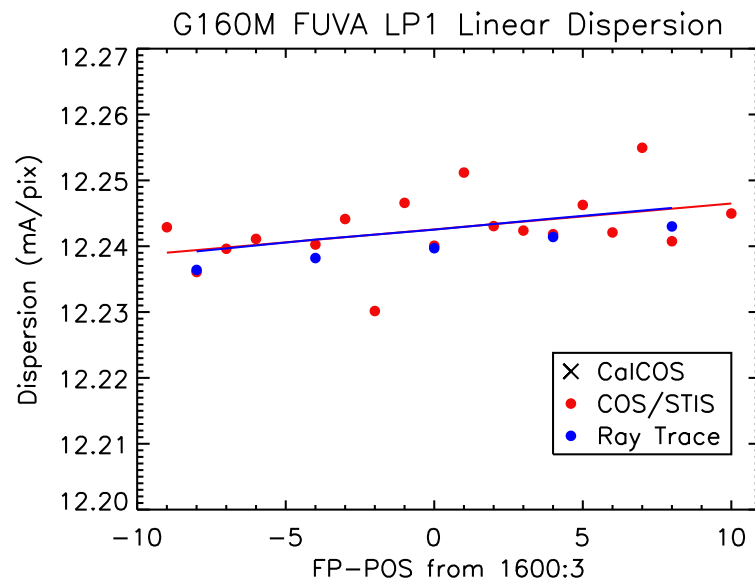
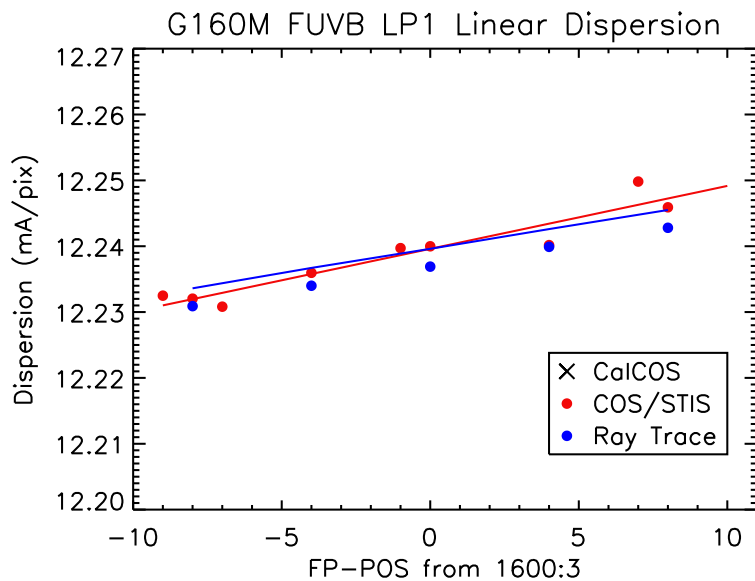
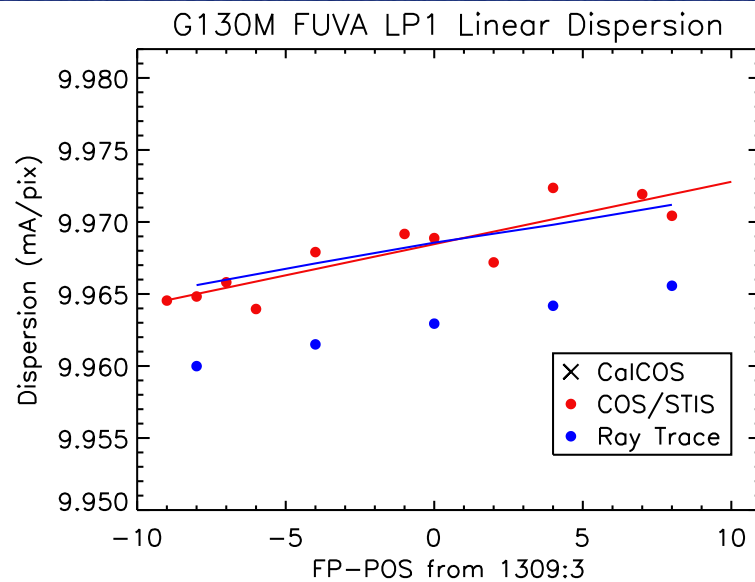
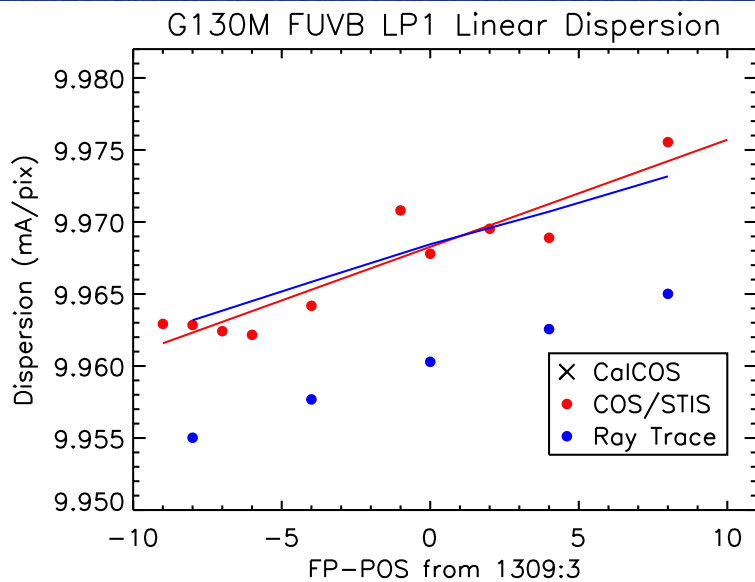
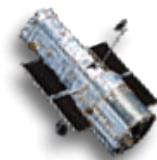


G160M FUGA Linear Dispersion



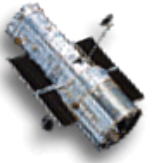


Matching COS/STIS Results and Ray Trace Models





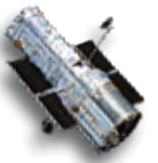
Updating Dispersion Solutions Ongoing Work



- Need to access if # of lines used to determine dispersion coefficients and their distribution on the detector is adequate
- Identify datasets where TA uncertainty is minimal and use those datasets to derive zero-point of wavelength solution
- Use AGN dataset compiled by B. Wakker and C. Danforth in addition to other datasets to test new dispersion solutions
 - Current wavelength dispersion reference file can support up to $n=3$ polynomial
 - No changes to pipeline required, only updated ref file, no other dependencies
- Investigate if difference between LP1 and LP2 dispersion coefficients is significant – both with models and from data
- Explore ray-trace models and see if can explain discrepancy between models and new coefficients by adjusting the focus in the models
 - If so, might be able to use ray-trace models coefficients for settings for which we have no overlapping COS + STIS data
- Release updated dispersion coefficients for most used settings in early 2016 and full set by ~ Summer 2016
- To improve dispersion solutions beyond ± 3 pix (and to that level in some localized regions) will need to improve x-walk and geometric distortion corrections



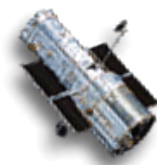
Detector Walk



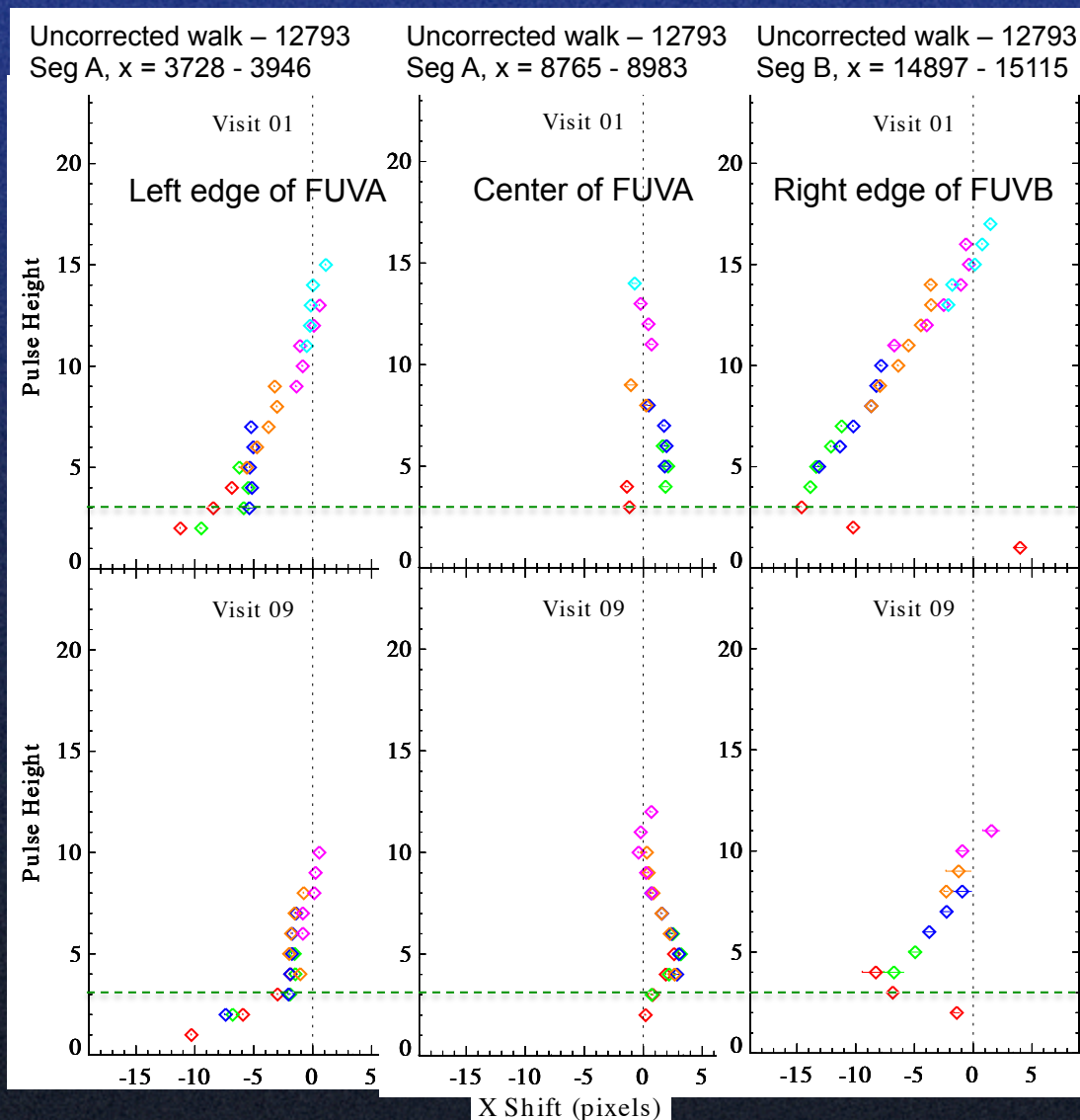
- Detector walk is the dependence of the calculated photon position on the pulse height (see e.g. Sahnou et al., 2011, SPIE proceedings, Vol 8859)
- Affects both the dispersion (x-walk) and cross-dispersion (y-walk) directions
- Figures in next slide are “interesting” examples of x-walk in the COS/FUV detector
 - x-walk is worse in some localized areas
- COS pipeline
 - Y-walk correction is currently applied
 - No x-walk correction is implemented



Walk Correction

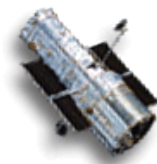


- Analyzing lamp data taken at different HV to evaluate x- and y-walk
 - Want to determine how the registration of events on the detector varies depending on the PHA
 - Affects both the dispersion (x) and cross-dispersion directions (y)
 - COS pipeline contains currently a y-walk correction only, that will be revisited in this work. Higher priority is to tackle the x-walk
 - x-walk varies in detector and in some areas can be up to ~6 pix, over the PHA range used in normal operations (PHA > 3, marked by green dashed line)
 - Edges of the detector are worse

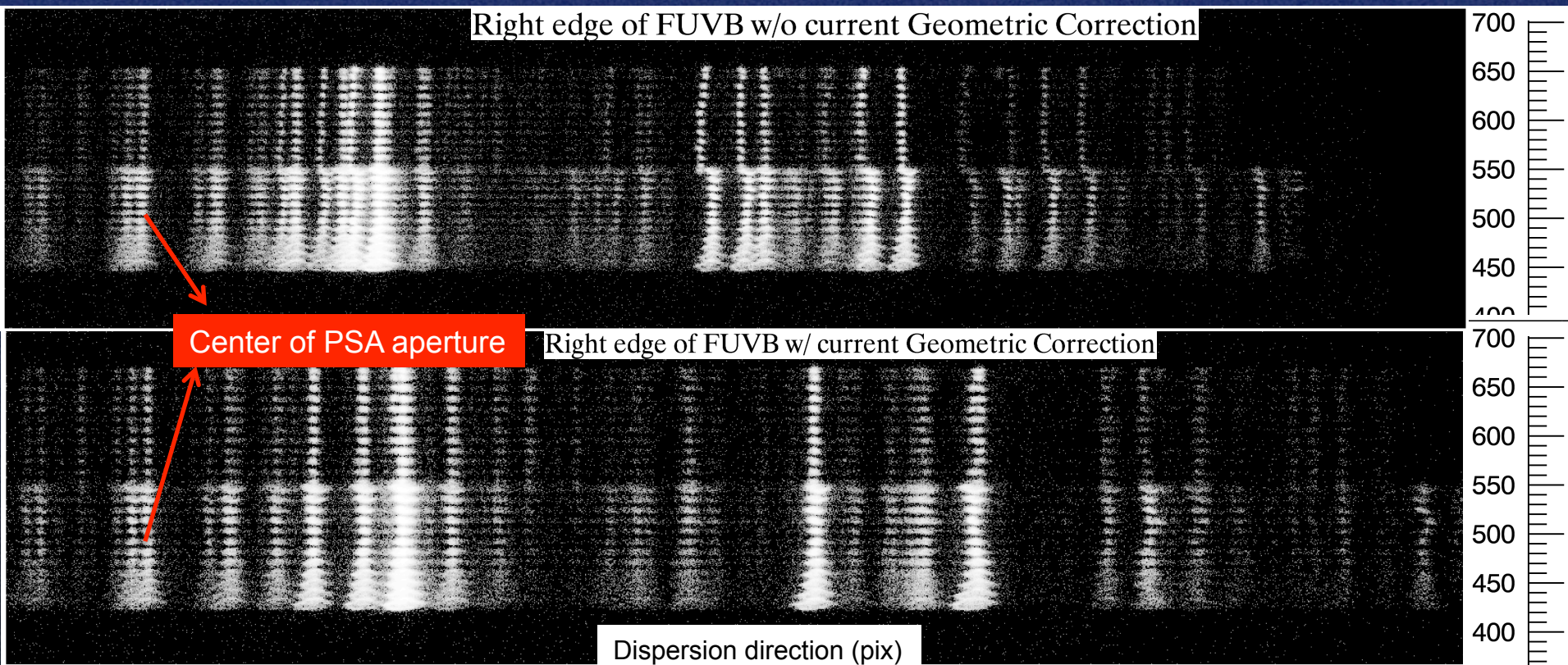




Geometric Distortion Correction

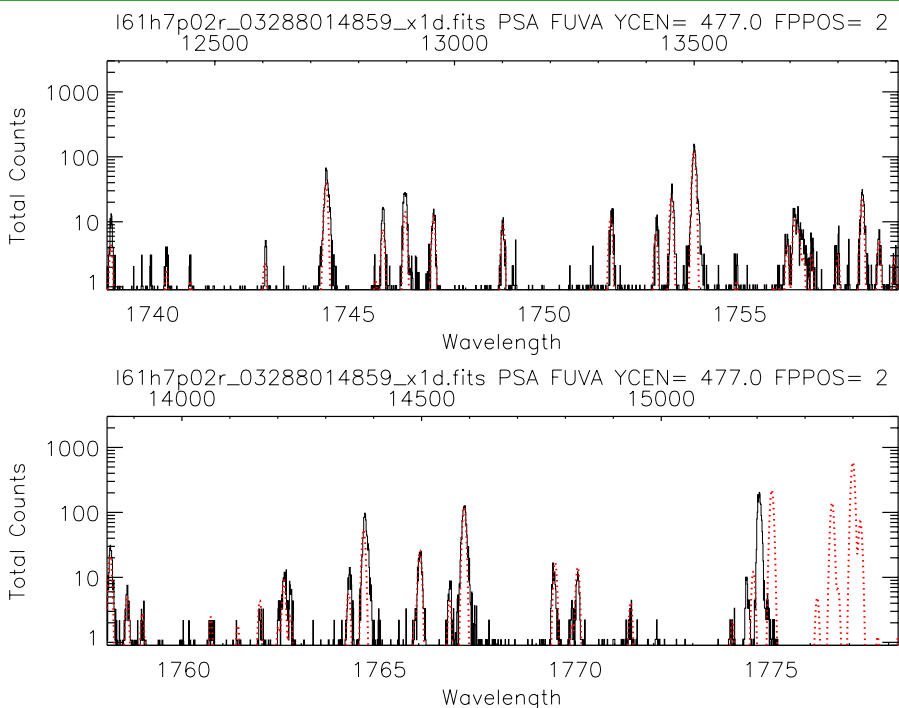


- Have processed through CalCOS the TV03 data used to determine geometric distortion correction to assess how well it does
 - Have a lamp line every 30 to ~ 200 pixels, so can only probe on those scales
 - Determined that 87% of the lines are within 3 pix of expected position (by fitting centroid of line)
 - Edge effects are very noticeable even in geometrically corrected data
- Figures show geometrically uncorrected (top) and corrected (bottom) data



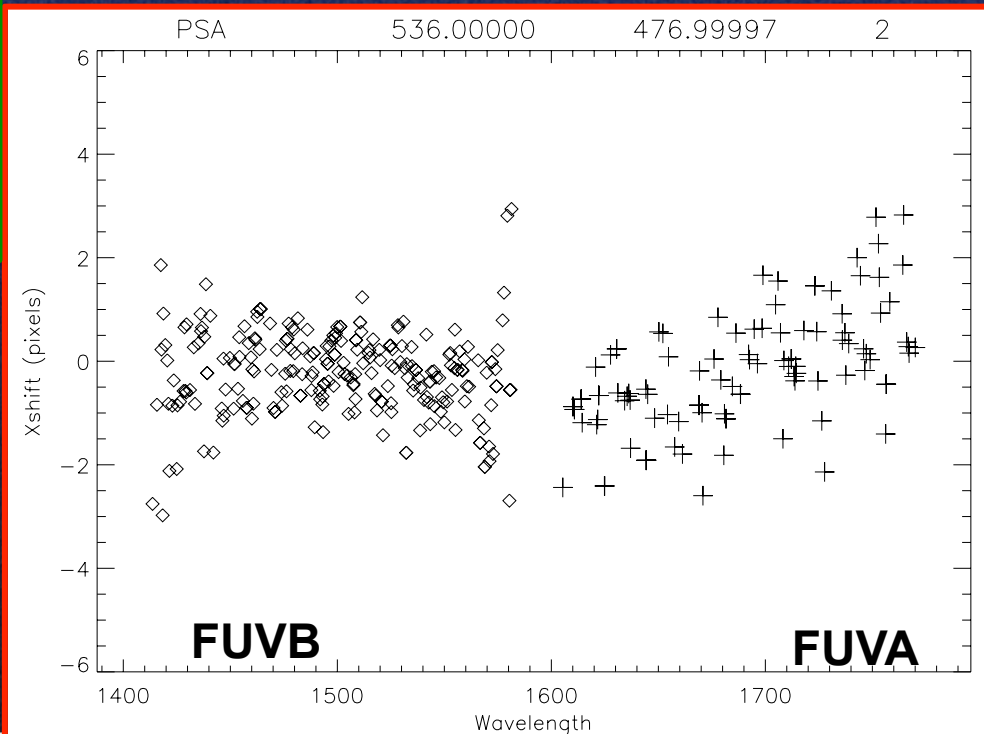


Matching NIST PtNe Line Atlas to Geometric Distortion TV03 Data



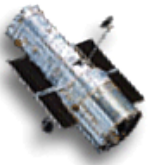
- Goal is to further improve geometric distortion correction
- NIST atlas is convolved with Gaussian LSF, line intensity is scaled to match COS
- Offsets between simulated (red line) and observed (black line) spectra are determined by cross-correlation

- Measured offsets shown for spectra obtained close to LP1 (TV location $\sim 1.2''$ above LP1)
- Preliminary measurements indicate that most offsets are within $\sim \pm 2$ pix
 \Rightarrow Geometric correction residuals not a huge factor in wavelength dispersion uncertainties





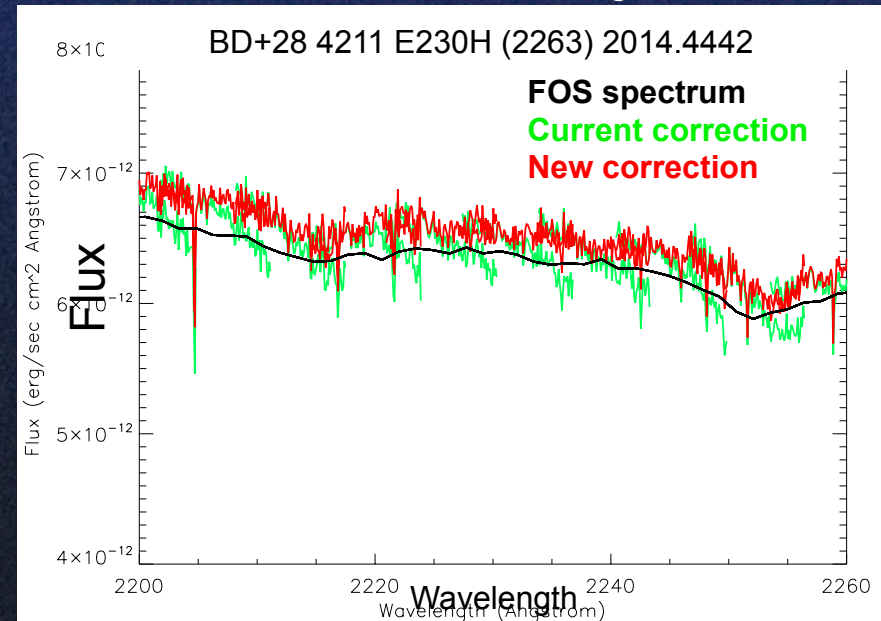
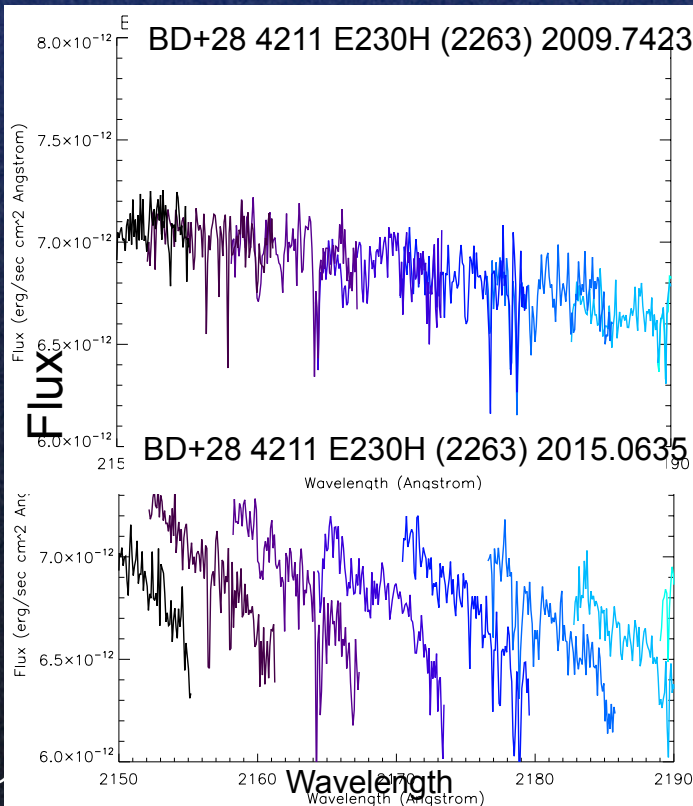
STIS Echelle Blaze Function (I)



- Blaze function characterizes grating efficiency along each spectral order
 - Spatial component: due to changes in location of spectrum on detector, due to mechanism non-repeatability
 - Temporal component: due to shifts in angle of grating grooves (epoxy?, contamination?)
 - Localized flux calibration errors up to 10-15%

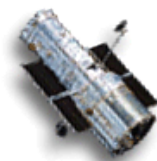
Analysis uses data from sensitivity monitoring programs:

- E140H (1416), E140M (1425), E230H (2263), and E230M (1978, 2707).
- Significant improvement has been achieved for E140H and E140M
- For E230M, the echelle blaze function shift was not as pronounced and the current version of ref. file does a good job
- For E230H, there is significant improvement for monitored 2263 setting; difficulty in extending correction to other cenwave settings



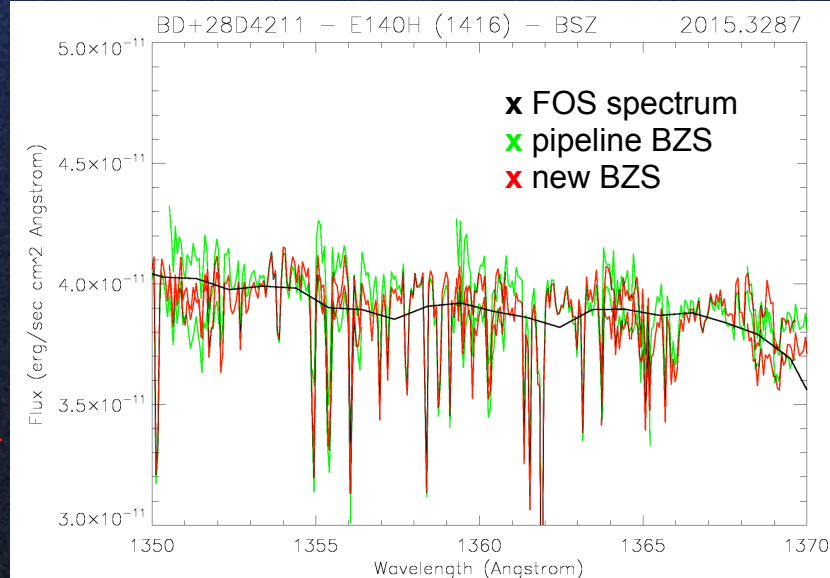
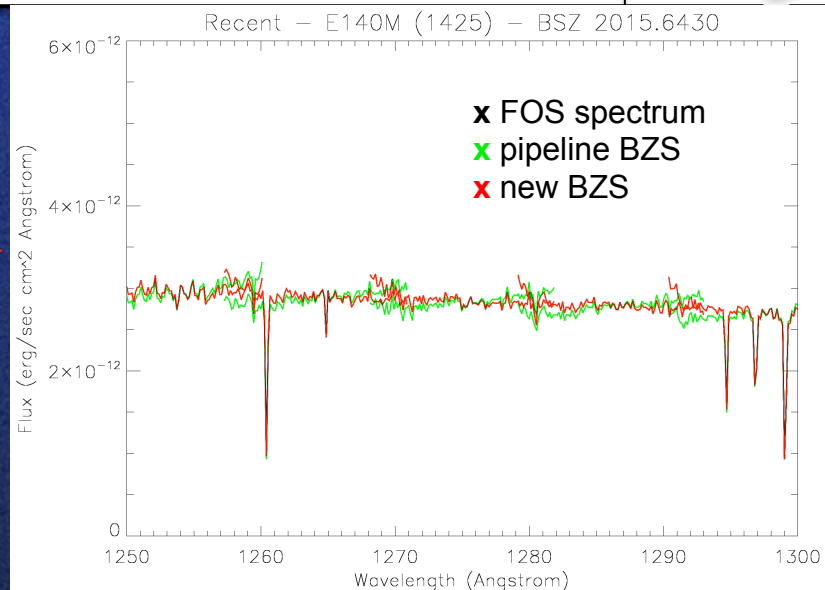


STIS Echelle Blaze Function (II)



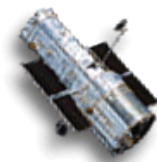
- Preparing new pipeline reference files for E140H, E140M, and E230M
- Correction introduces some artifacts on some E140H/E140M orders, which need to be investigated prior to delivery
 - May be related to extrapolating blaze function beyond initial measurements
 - Evaluating whether reference file modifications might fix this
 - Alternatively, could flag extrapolated regions as bad, but this would require a CalSTIS code change
- After finalizing other gratings will consider a wider range of data to determine E230H corrections as a function of CENWAVE

Section of E140H shows some improvement with new correction added (red curve), but significant discrepancies between orders remain

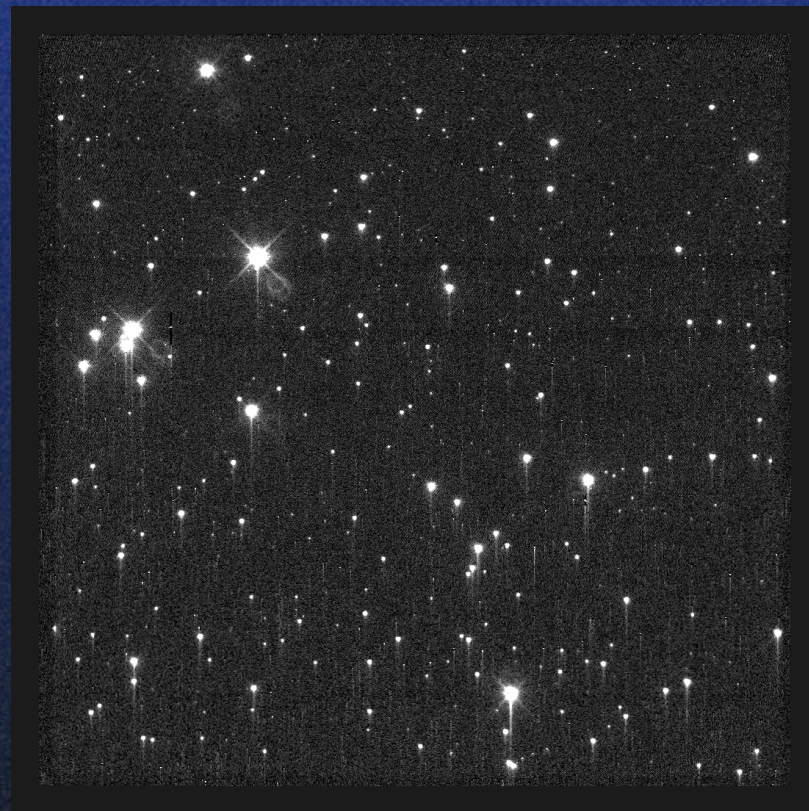




STIS CCD Pixel Based CTE Correction



- COS/STIS released new stand-alone pixel based CTE correction for STIS/CCD
 - Using scripts derived from ACS pipeline correction work
 - Tool includes correction of darks & recalibration
 - Tool and cookbook released in September 2015



http://www.stsci.edu/hst/stis/software/analyzing/scripts/pixel_based_CTI